

# FINAL REVIEW

## Taylor series

$$T_n(x) = \sum_{k=0}^n \frac{f^{(k)}(b)}{k!} (x-b)^k$$

$$\text{Error} = |f(x) - T_n(x)| \leq \frac{M}{(n+1)!} |x-b|^{n+1}$$

\* Where  $|f^{(n+1)}(x)| \leq M$   
on the interval

steps to solving error on given interval  $I = [c, d]$

- ① Find the next derivative  $(f^{(n+1)}(x))$
- ② Find  $M$  by finding the biggest that  $|f^{(n+1)}|$  will ever get on interval
- ③ plug  $M$  into error formula

Taylor Series! \* know all of the listed series

$$f(x) = \sum_{k=0}^{\infty} \frac{1}{k!} f^{(k)}(b) (x-b)^k = \lim_{n \rightarrow \infty} T_n(x)$$

open interval of convergence

$\int$  to integrate a Taylor series  $\Rightarrow$  change  $x^k$  to  $\frac{1}{k+1} x^{k+1}$

$\frac{d}{dx}$  to differentiate a Taylor series  $\Rightarrow$  change  $x^k$  to  $kx^{k-1}$

Substitution Questions  $\Rightarrow$  rearrange to fit  
one of the known series and fit in  $x$

Combining Questions  $\Rightarrow$  add series, smallest  
convergence sticks

Integrating Questions

# EXAM 2 REVIEW

13.4 - 14.3

## 13.4 - Motion in Space

$t = \text{time}$   $r(t) = \langle x(t), y(t), z(t) \rangle = \text{position}$

$v(t) = r'(t) = \text{velocity vector}$

$|v(t)| = |r'(t)| = \text{speed function}$

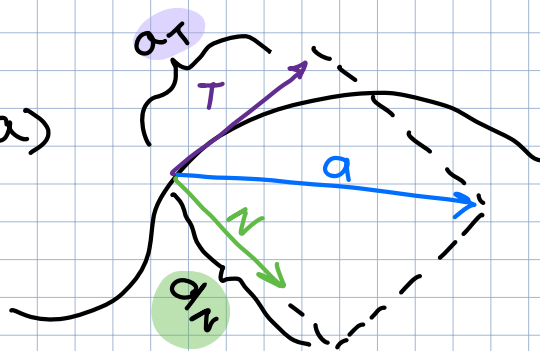
$a(t) = r''(t) = \text{acceleration vector}$

components of acceleration

$$a_T = \frac{r'(t) \cdot r''(t)}{|r'(t)|}$$

$$a_N = \frac{|r'(t) \times r''(t)|}{|r'(t)|^2}$$

$$a_T = \text{Comp}_T(a)$$



$$a_N = \text{Comp}_N(a)$$

\* application

Newton's second law  $\Rightarrow F(t) = ma(t)$

force vector = mass (acceleration vector)

## 14.1 - Functions of several variables

$z = f(x, y) \Rightarrow z$  is height above  $xy$ -plane

\* if one variable is fixed then only 2 variables  
ex:  $z = f(4, y) \rightarrow x = 4, y$  changes + function of  $y$

\* Domain restriction rules:

$$z = \sqrt{\text{Blah}} \Rightarrow \text{Blah} \geq 0 \quad z = \sin^{-1}(\text{Blah})$$

$$z = \frac{1}{\text{Blah}} \Rightarrow \text{Blah} \neq 0 \quad z = \cos^{-1}(\text{Blah})$$

$$z = \ln(\text{Blah}) \Rightarrow \text{Blah} > 0 \quad -1 \leq \text{Blah} \leq 1$$

\* to graph level curves, fix  $z$  at different values

### 14.3 - Partial Derivatives

$f_x$  = slope in the  $x$  direction

$f_y$  = slope in the  $y$  direction

when facing parallel to  $x$ -axis ...

- if  $f_x$  is negative, walking down hill
- if  $f_x$  is positive, walking up hill

→ Same for  $y$

$f_{xx}$  = concavity in  $x$ -direction

$f_{yy}$  = concavity in  $y$ -direction

$f_{xy}$  = mixed partial =  $f_{yx}$  ← always the same

### 14.4 - Tangent Planes

↳ the plane that contains all tangent lines to a surface at a point

$$z - z_0 = f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0)$$

tangent plane approx. / linear approximation

$$\begin{cases} \rightarrow F(x, y) \approx L(x, y) = f(x_0, y_0) + f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0) \\ \text{if } (x, y) \text{ is "near" } (x_0, y_0) \end{cases}$$

### 14.7 - Max and Min values

↳ be able to find critical points and classify them + find absolute max + min

\* Critical point  $\Rightarrow f_x(a, b) = 0$  and  $f_y(a, b) = 0$   
or where either DNE

\* Second Derivative test

$$(a, b) = \text{critical point}; D = f_{xx}(a, b)f_{yy}(a, b) - [f_{xy}(a, b)]^2$$

$D > 0$  and  $f_{xx} > 0$  = local min

$D > 0$  and  $f_{xx} < 0$  = local max

$D < 0$  = saddle point       $D = 0 \Rightarrow$  inconclusive

\* absolute max/min occur @ critical point or on boundary of given region

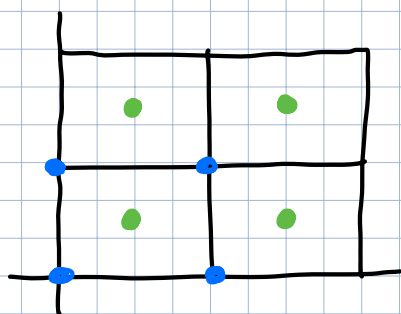
- (1) Find critical values and plug into  $f(x,y)$
- (2) Find formulas for each part of boundary and find values of  $f(x,y)$  at these points
- (3) Absolute max = biggest output  
Absolute min = smallest output

\* applied optimization

## 15.1 - Double Integrals over Rectangular Regions

$\iint_R f(x,y) dA$  = the volume under the surface and above the  $xy$ -plane

approximation



$m$  = columns > compute area of one rectangle  
 $n$  = rows

$$\text{volume} = (\text{height}) (\Delta A) = f(x,y) \Delta A$$

lower left endpoints

midpoint rule

Sum up all volumes

$$\text{Average value} = \frac{1}{\text{area } R} \iint_R f(x,y) dA$$

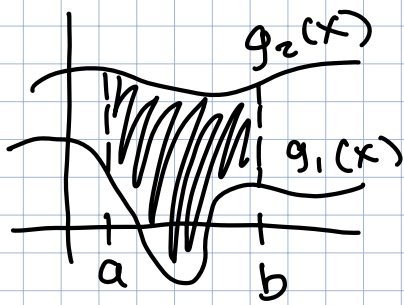
## 15.2 - Iterated Integrals

$$\int_a^b \int_c^d f(x,y) dy dx = a \leq x \leq b \quad c \leq y \leq d$$
$$= R = [a,b] \times [c,d]$$

Rectangles  $\nearrow$

General  $\searrow$

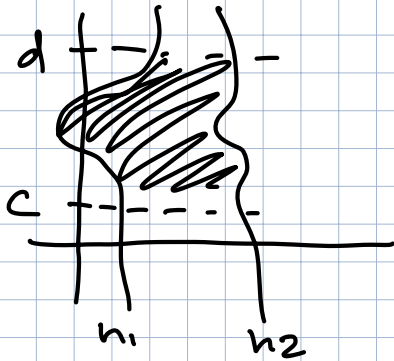
"Switch the order of integration"



Top/Bottom regions

$$a \leq x \leq b \quad g_1(x) \leq y \leq g_2(x)$$

$$\int_a^b \int_{g_1(x)}^{g_2(x)} F(x,y) dy dx$$



Right/Left regions

$$c \leq y \leq d \quad h_1(y) \leq x \leq h_2(y)$$

$$\int_c^d \int_{h_1(y)}^{h_2(y)} F(x,y) dx dy$$

Steps to solve:

(1) Find integrand  $\Rightarrow$  solve for  $z$ , if there are two, set up two double integrals and subtract @ end

(2) Region  $\Rightarrow$  graph on  $xy$ -plane,  $z$ s intersect

### 10.3 - Polar Coordinates

$$(r, \theta) \quad x = r \cos \theta \quad y = r \sin \theta \quad x^2 + y^2 = r^2 \quad \tan \theta = \frac{y}{x}$$

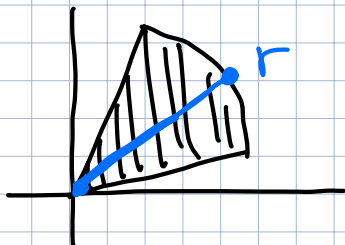
Plot points!

### 15.3 - Double Integrals in Polar Coordinates

$$\iint_D F(x,y) dA = \int_a^B \int_a^b F(r \cos \theta, r \sin \theta) r dr d\theta$$

$$\iint_D 1 dA = \text{"Area of D"}$$

↑  
"Inside-  
outside"



# EXAM 1 REVIEW

12.1 - 13.3

## 12.1 - 3D Coordinate Systems

Point  $P = (a, b, c)$

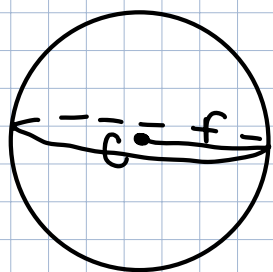
$\mathbb{R}^2 = 2D$  set of points

distance from... (yz, xz, xy)

vs.  $\mathbb{R}^3 = 3D$  set of points

Distance between two points =

$$\sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$



$$\sqrt{(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2} = r$$

→ turns into equation of sphere

Center =  $(x_0, y_0, z_0)$

Points @ distance  $r$  from  $C = (x, y, z)$

## 12.2 - Vectors

Adding vectors



$$u + v = w$$

• 2 non-zero vectors are parallel if they are scalar multiples

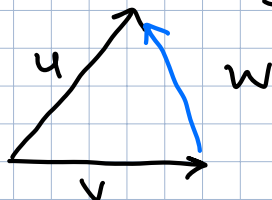


if negative, opp. direction

$A(x_1, y_1, z_1)$   $B(x_2, y_2, z_2)$

$$\vec{AB} = \langle x_2 - x_1, y_2 - y_1, z_2 - z_1 \rangle$$

Subtracting vectors



$$u - v = w$$

length / magnitude =

$$\sqrt{x^2 + y^2 + z^2}$$

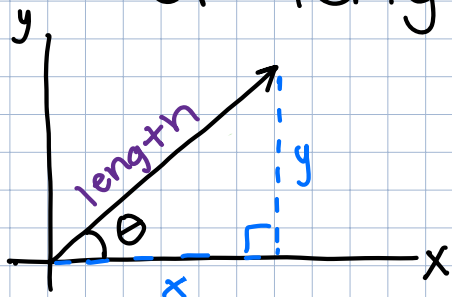
use to scale unit vector of length 1

unit vector

$$\frac{1}{|v|} \langle v \rangle$$

$$\langle 1, m \rangle =$$

a vector parallel to any line with slope  $m$



## 12.3 - The Dot Product

$$a = \langle a_1, a_2, a_3 \rangle \quad b = \langle b_1, b_2, b_3 \rangle$$

$$a \cdot b = a_1 b_1 + a_2 b_2 + a_3 b_3$$

result = scalar #, not vector

If  $\theta$  is the angle between two non-zero vectors when drawn tail to tail...

$$a \cdot b = |a||b|\cos\theta$$

If  $a$  and  $b$  are perpendicular...  $a \cdot b = 0$

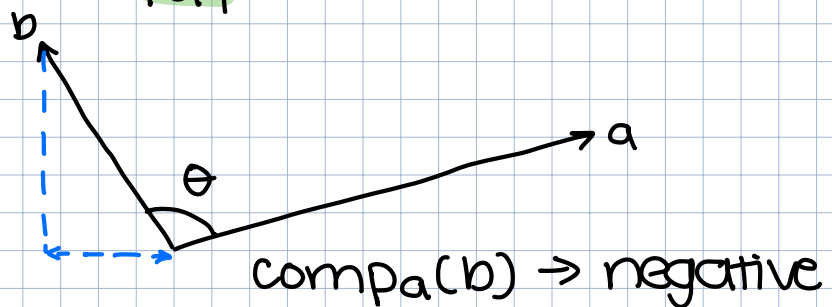
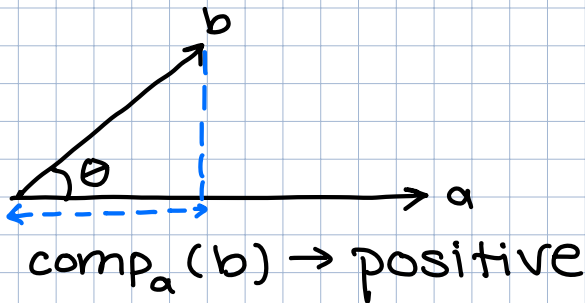
If  $a$  and  $b$  are parallel and in same direction...  $a \cdot b = |a||b|$

→ opposite direction...  $a \cdot b = -|a||b|$

### Projections

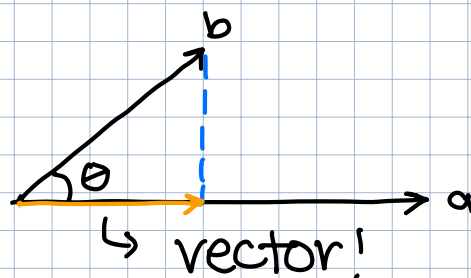
- the scalar/component projection of  $b$  onto  $a$  is the length of the projection...

$$\text{Comp}_a(b) = \frac{a \cdot b}{|a|}$$



- the vector projection of  $b$  onto  $a$  is the actual vector you get from the projection...

$$\text{proj}_a(b) = \left( \frac{a \cdot b}{|a|^2} \right) a$$



$$\text{WORK} = F \cdot D$$

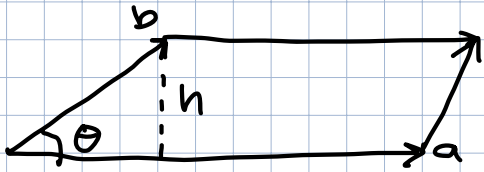


## 12.4 - The Cross Product

$$\mathbf{a} \times \mathbf{b} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix} = (a_2 b_3 - a_3 b_2) \mathbf{i} - (a_1 b_3 - a_3 b_1) \mathbf{j} + (a_1 b_2 - a_2 b_1) \mathbf{k}$$

→ vector! Not scalar!

is orthogonal to  $\mathbf{a}$  and  $\mathbf{b}$  ← use as a check!



area of parallelogram =

$$|\mathbf{a} \times \mathbf{b}| = |\mathbf{a}| |\mathbf{b}| \sin \theta$$

OR

$$|\mathbf{a}| h = |\mathbf{a}| |\mathbf{b}| \sin \theta$$

area of triangle =

$$\frac{1}{2} |\mathbf{a} \times \mathbf{b}|$$

2 non-zero vectors are parallel if...

$$\mathbf{a} \times \mathbf{b} = \mathbf{0}$$

## 12.5 - Lines and Planes

### Lines

Let  $(x_0, y_0, z_0)$  be a point on the line and let  $\langle a, b, c \rangle$  be any vector parallel...

parametric eq =

$$x = x_0 + at$$

$$y = y_0 + bt$$

$$z = z_0 + ct$$

need  
- point  
- direction

Symmetric eq =

$$\frac{x-x_0}{a} = \frac{y-y_0}{b} = \frac{z-z_0}{c}$$

• Two lines are parallel if their direction vectors are parallel

### Planes

Let  $(x_0, y_0, z_0)$  be a point on a plane and let  $\langle a, b, c \rangle$  be any vector normal...

standard form =

$$a(x-x_0) + b(y-y_0) + c(z-z_0) = 0$$

vector form =

$$\langle a, b, c \rangle \cdot \langle x-x_0, y-y_0, z-z_0 \rangle = 0$$

• Two planes are parallel if their normal vectors are parallel

• If 2 planes are not parallel, they must intersect to form a line

//

- Two lines intersect if they have an  $(x, y, z)$  point in common



use different parameters when you combine

- Two lines are skew if they don't intersect and aren't parallel

↓

$$\vec{n}_1 \cdot \vec{n}_2 = |\vec{n}_1| |\vec{n}_2| \cos \theta$$

The planes are orthogonal if their normal vectors are orthogonal

## 12.6 - Cylinders and Quadratic Surfaces

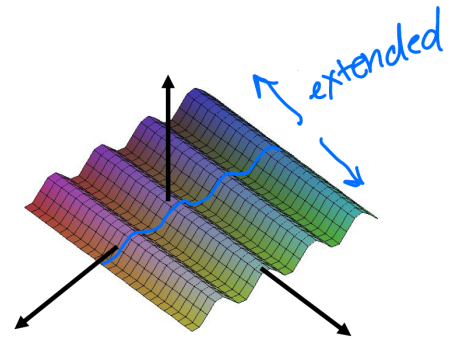
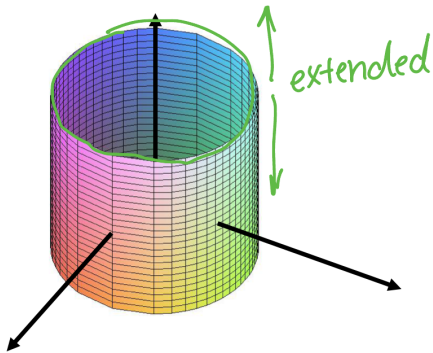
Cylinders - If one variable is absent

$$x^2 + y^2 = 1$$

circular cylinder!

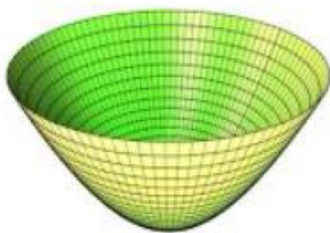
$$z = \cos(x)$$

cosine cylinder!



## Quadratic Surfaces

use tracing!



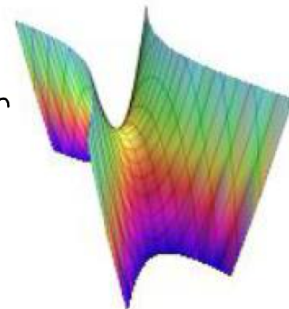
Elliptical/Circular Paraboloid

$$\frac{z}{c} = \frac{x^2}{a^2} + \frac{y^2}{b^2}$$

(ex:  $z = 3x^2 + 5y^2$ )

$3x^2 + 5y^2 \rightarrow$  when  $z$  is fixed, ellipse in 2D

if hyperbola in 2D



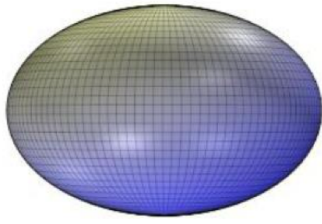
Hyperbolic Paraboloid

$$\frac{z}{c} = \frac{x^2}{a^2} - \frac{y^2}{b^2}$$

(ex:  $y = 2x^2 - 5z^2$ )

When all three variables are squared...

all positive

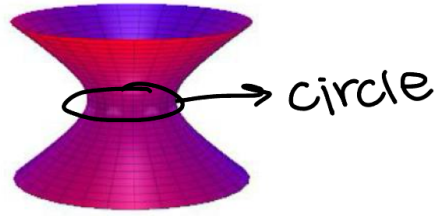


Ellipsoid/Sphere

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$$

(ex:  $3x^2 + 5y^2 + z^2 = 3$ )

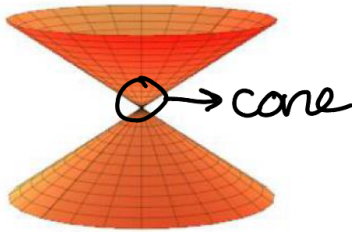
one negative



Hyperboloid of One Sheet

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = \textcircled{1} \text{ Positive}$$

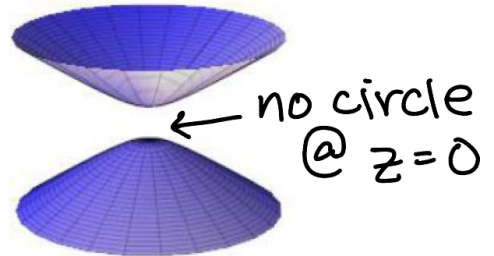
(ex:  $x^2 - y^2 + z^2 = 10$ )



Circular/Elliptical Cone

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = \textcircled{0} \text{ zero}$$

(ex:  $z^2 = x^2 + y^2$ )



Hyperboloid of Two Sheets

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = \textcircled{-1} \text{ negative}$$

(ex:  $x^2 + y^2 - z^2 = -4$ )

### 13.1 - Vector Curves

parametric form:  $x = f(t)$ ,  $y = g(t)$ ,  $z = h(t)$

vector form:  $r(t) = \langle f(t), g(t), h(t) \rangle$

↳ position vector that points from origin to curve

To visualize 3D curves...

- ① Find surface/path of motion by eliminating  $t$  variable
- ② Plot points

with circular motion...

$\sin^2(t) + \cos^2(t) = 1$  so if ...

$$x = r \cos(t), y = r \sin(t) \longrightarrow x^2 + y^2 = r^2$$

# Intersection

- ① Intersecting a curve and a surface  
↳ combine conditions!

Find the intersection of  
 $x = t, y = \cos(\pi t), z = \sin(\pi t)$   
and

$(x^2 - y^2 - z^2 = 3) - 1$   
 $-x^2 + y^2 + z^2 = -3$  ←  
Hyperboloid of 2 sheets

$y^2 + z^2 = 1$

-----

$t^2 - \cos^2(\pi t) - \sin^2(\pi t) = 3$

$t^2 - 1 = 3$

$t^2 = 4$

$t = \pm 2$

intersection points

$(x, y, z) = (2, 1, 0)$   
 $(x, y, z) = (-2, 1, 0)$

- ② Intersecting two curves

↳ use different parameters + combine!

Given:

$$r_1(t) = \langle 2t, 3t^2, 2t^3 \rangle$$

$$r_2(t) = \langle 2 - 2t, 3 + 3t, 2 - 6t \rangle$$

Find the  $(x, y, z)$  point(s) at which the paths of the two particles described cross.

①  $2t = x = 2 - 2u \rightarrow u = 1 - t$

②  $3t^2 = y = 3 + 3u \rightarrow t^2 = 1 + u \rightarrow t^2 = 1 + 1 - t$

③  $2 + 3 = z = 2 - 6u$

$$t^2 = 2 - t$$

$$t^2 + t - 2 = 0$$

$$(t - 1)(t + 2) = 0$$

$$t = 1, -2$$

$$u = 1 - 1 \quad u = 1 + 2$$

$$u = 0, 3$$

@  $t = 1, u = 0$

$$x = -4$$

$$y = 12$$

$$z = 2$$

@  $t = -2, u = 3$

$$x = 2$$

$$y = 3$$

$$z = -16$$

$$(-4, 12, 2) \text{ and } (2, 3, -16)$$

### ③ Intersecting two surfaces

↳ parameterize the curve by:

a) let one variable be  $t$ ,  
solve for others in terms  
of  $t$

OR if circle/ellipse

$$b) \frac{x^2}{a^2} + \frac{y^2}{b^2} = 1 \leftrightarrow \begin{cases} x = a \cos(t) \\ y = b \sin(t) \end{cases}$$

### 13.2 - Calculus for vector curves

If  $r(t) = \langle x(t), y(t), z(t) \rangle$  then...

$r'(t) = \langle x'(t), y'(t), z'(t) \rangle =$  a vector tangent to the curve at  $t$

$T(t) = \frac{1}{|r'(t)|} r'(t) =$  unit tangent vector

$$\int r(t) dt = \left\langle \int x(t) dt, \int y(t) dt, \int z(t) dt \right\rangle$$

(each has its own  $C$ )

Equation for the tangent line to  $(x(t), y(t), z(t))$  at  $t = a$ ...

$$\begin{aligned} x &= x(a) + x'(a)u \\ y &= y(a) + y'(a)u \\ z &= z(a) + z'(a)u \end{aligned}$$

$r'(a) =$   
direction  
vector

\* If you need the angle of intersection of two curves, you need the angle between their tangent vectors at their intersection

### 13.3 - Tools for Analyzing vector curves

#### Arc Length

If  $r(t) = \langle x(t), y(t), z(t) \rangle$  then...

distance traveled from  $t = a$  to  $t = b =$

$$\int_a^b |r'(t)| dt = \int_a^b \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2 + \left(\frac{dz}{dt}\right)^2} dt$$

